

Automated Decision-Making on Networks with LLMs through Knowledge-Guided Evolution

Xiaohan Zheng, Lanning Wei, Yong Li, Quanming Yao*

Department of Electronic Engineering, Tsinghua University
zhengxh23@mails.tsinghua.edu.cn, weilanning@163.com, liyong07@tsinghua.edu.cn,
qyaoaa@tsinghua.edu.cn

Abstract

Effective decision-making on networks often relies on learning from graph-structured data, where Graph Neural Networks (GNNs) play a central role, but they take efforts to configure and tune. In this demo, we propose LLMNet, showing how to design GNN automated through Large Language Models. Our system develops a set of agents that construct graph-related knowledge bases and then leverages Retrieval-Augmented Generation (RAG) to support automated configuration and refinement of GNN models through a knowledge-guided evolution process. These agents, equipped with specialized knowledge bases, extract insights into tasks and graph structures by interacting with the knowledge bases. Empirical results show LLMNet excels in twelve datasets across three graph learning tasks, validating its effectiveness of GNN model designing.

1 Introduction and Related Work

Effective decision-making in networks—such as in communication networks, social networks, and transportation networks—often relies on graph-structured data representations. Among the techniques developed for learning from such data, Graph Neural Networks (GNNs) have become widely adopted across diverse domains, including tasks such as anomaly detection and recommendation systems in social networks [Hamilton *et al.*, 2017], as well as for predicting biomedical molecular properties [Gilmer *et al.*, 2017]. The majority of existing GNNs are designed for diverse graphs under a specific task [Wu *et al.*, 2020], such as capturing graph-level representations [Zhang *et al.*, 2018; Ying *et al.*, 2018]. and learning subgraph patterns in link-level tasks [He *et al.*, 2020; Zhang and Chen, 2018]. However, designing effective GNNs for different graph learning problems is challenging, as it requires substantial graph-related knowledge in order to understand the tasks and graphs [Hoffman *et al.*, 1995]. Then, there is a natural question: *How to integrate graph learning knowledge to design effective GNNs?* It is non-trivial to answer this question. Firstly,

existing methods have not provided explicit guidelines for utilizing knowledge in designing GNN model architectures. Most GNNs are designed to effectively model graphs for a specific task [Wu *et al.*, 2020; Hamilton *et al.*, 2017; Ying *et al.*, 2018], based on implicit human expertise, which is difficult to explicitly describe and extract.

Therefore, we propose LLMNet, which automates GNN design using LLMs. Specifically, we have designed a Knowledge Agent to extract graph-related knowledge, building knowledge bases covering advanced graph learning research. Then, we have developed a set of agents that use RAG (Retrieval-Augmented Generation) to interact with knowledge bases, designing GNNs step by step in a knowledge-guided manner. Leveraging LLMs’ task analysis, LLMNet streamlines the designing and refinement of GNN model architectures. Extensive experiments on twelve datasets across three tasks demonstrate LLMNet’s superior performance and efficiency, proving the effectiveness of integrating knowledge for automated GNN design. A concrete case demonstrating this process is presented in Section 4.

2 Method

We introduce LLMNet, which prepares and utilizes knowledge to design GNN model architectures for diverse graph learning tasks using LLM-based agents. Firstly, we gather graph-related resources and develop a knowledge agent for knowledge extraction and retrieval. Subsequently, the knowledge is then used by several LLM-based agents step by step to design effective GNN model architectures.

2.1 Knowledge Bases Construction and Utilization

Knowledge Bases Construction LLMs face challenges due to outdated knowledge and hallucinations. We address this by creating two knowledge bases, which is currently lacking for designing GNN model architectures. We collect resources and use the Knowledge Agent to manage them.

The Knowledge Agent is tasked with acquiring and integrating specialized knowledge tailored to specific user requirements. This agent mainly manages two types of knowledge bases, as shown in Figure 1: the prior knowledge base and the experiment knowledge base. The prior knowledge base is enriched with task-specific information extracted from sources such as the Open Graph Benchmark (OGB) leaderboards, the PyTorch Geometric (PyG) documentation, and the top-tier conference proceedings that are accessible on Arxiv,

*Corresponding author

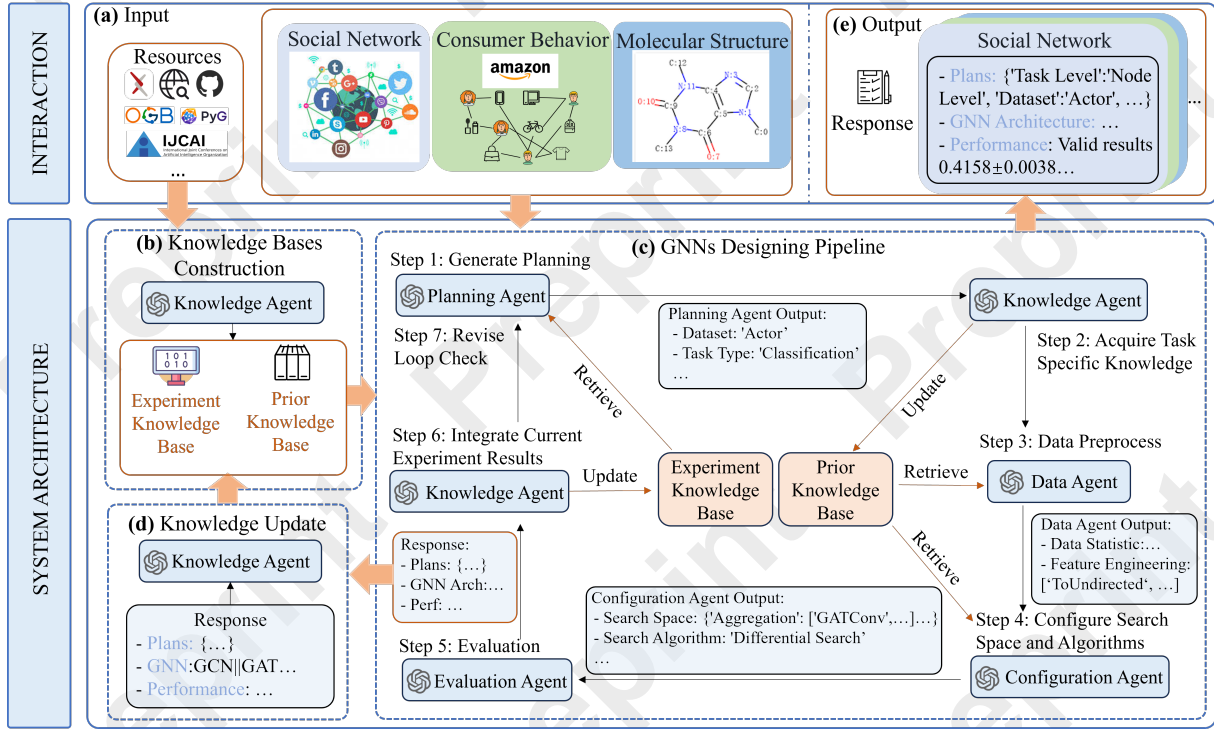


Figure 1: System architecture of LLMNet, which automates GNN design via a knowledge-guided approach. (a) Inputs: task graph and external knowledge resources. (b) Knowledge Agent builds knowledge bases. (c) The pipeline of LLM agents designs and finetunes GNNs using the knowledge. (d) User receives intermediate responses and experimental knowledge base is updated. (e) Outputs: GNN design, performance, and resource usage.

ensuring the agent remains at the cutting edge of technology and methodology. The experiment knowledge base archives detailed experimental outcomes such as the benchmark evaluation results, including models setups and their performance on specific datasets, thereby providing insights into their effectiveness and application contexts.

The content of papers and reports often overlaps, with redundant background information and methods that can introduce noise and reduce the informativeness of retrieved knowledge. To address this, we employ a two-level knowledge extraction strategy, first, we start by summarizing inputs to obtain coarse-grained knowledge, then refine this into fine-grained details specific to graph learning tasks, such as architecture design and dataset usage. The code and the extended version with more details are available.¹

Knowledge Utilization and Update To effectively utilize the constructed knowledge bases, we implement a goal-aware knowledge retrieval mechanism. Utilizing the RAG technique, we enhance the effectiveness of the designing GNN model architectures by retrieving relevant knowledge. The pre-trained model all-MiniLM-L6-v2 encodes both the extracted knowledge and the queries from other agents. We calculate the cosine similarity in the embedding space to identify the most relevant knowledge. To accommodate the varying goals and resource types in graph learning, we apply a post-ranking strategy. The top- k knowledge items from each resource type are initially retrieved and then re-ranked and se-

lected by the knowledge agent based on the query’s context. This refined knowledge is integrated into the graph learning agent’s prompt, facilitating the design of GNN model.

LLMNet also incorporates a dynamically knowledge update mechanism. After the evaluation of a GNN model, the experimental summary, including the task plan, designed GNNs, and results, is stored in memory. The planning agent then compiles a report, which is added to the knowledge base, ensuring that the system’s knowledge remains current and applicable for future pipeline runs. This continuous update process allows LLMNet to adapt and improve over time, enhancing its ability to design effective GNN models.

2.2 Knowledge-Guided GNNs Model Designing

Figure 1 illustrates how each agent engages with knowledge bases to streamline the entire process. The two knowledge bases bridge research and application, they empower agents to make informed decisions.

Planning Agent The Planning Agent generate a task plan based on user instructions, to direct subsequent agent actions, which includes specifications for datasets, task types and evaluation metrics. After all agents completed their tasks, this agent evaluates the experimental results, utilizing insights from the experiment knowledge base to determine whether a revision loop is necessary.

Data Agent The Data Agent utilizes insights from the prior knowledge base to perform feature engineering tailored to specific graphs and tasks, ensuring alignment with expert practices in a knowledge-guided manner.

¹<https://github.com/Igssstsp/LLMNet>

	Cora	Photo	Actor	Genius	ogbn-arxiv	DD	Proteins	ogbg-molhiv	Amazon-Sports(↓)	Avg. Rank
LLMNet	87.10(0.36)	96.11(0.33)	40.93(0.35)	90.89(0.11)	72.70(0.54)	78.27(2.57)	75.44(0.93)	74.27(1.54)	0.9298(0.0071)	1
LLMNet (GL)	86.68(0.40)	95.50(0.21)	39.59(0.39)	90.33(0.15)	72.30(0.54)	77.69(2.24)	74.88(1.16)	73.37(1.23)	0.9622(0.0103)	2.5
GCN	85.68(0.61)	93.13(0.27)	33.98(0.76)	89.10(0.13)	71.74(0.29)	73.59(4.17)	74.84(3.07)	73.89(1.46)	1.0832(0.0077)	5.25
SAGE	86.18(0.35)	94.60(0.25)	39.28(0.18)	89.71(0.09)	71.49(0.27)	76.99(2.74)	73.87(2.42)	73.46(1.69)	0.9900(0.0125)	4.5
AutoML	86.57(0.32)	95.38(0.30)	40.39(0.03)	90.81(0.04)	72.42(0.37)	77.03(2.48)	74.58(2.61)	73.51(3.21)	0.9327(0.0006)	2.63
LLM-GNN	84.64(1.04)	93.73(0.38)	38.92(0.07)	89.31(0.17)	70.83(0.93)	75.12(3.44)	74.47(3.65)	72.93(0.90)	0.9670(0.0079)	5.13

Table 1: Performance of LLMNet and baselines on three tasks. We report the test accuracy and the standard deviation for node and graph classification tasks, and use the common Rooted Mean Square Error (RMSE) for the item ranking task. The top-ranked performance in each dataset is highlighted in gray, and the second best one is underlined. The average rank on all datasets is provided in the last column.

Configuration Agent The Configuration Agent is responsible for configuring the search space, which includes possible model architecture configurations such as layers and connections, and the search algorithm that explores this space. It interacts with the prior knowledge base to gain insights on model design, enhancing the effectiveness of search space configuration and algorithm selection.

Evaluation Agent The Evaluation Agent is designed to fine-tune the designed GNN and conduct experiments to validate its performance. After completing the experiments, the Evaluation Agent transmits the results to the Knowledge Agent for integration into the experiment knowledge base.

3 Experiments

We evaluate LLMNet’s effectiveness on twelve datasets across three tasks as shown in Table 1, the performance of another three datasets are shown in appendix of extended version. Detailed resource costs and ablation studies are in the appendix of the extended version.

3.1 Experimental Settings

Datasets We evaluate twelve widely used datasets across three tasks as shown in Table 1. The detailed introduction of these datasets and the evaluation performance of another three datasets are shown in appendix of extended version.

Baselines In this paper, we provide several kinds of baselines. (1) GNNs with task adaption, including GCN [Kipf and Welling, 2016] and GraphSAGE [Hamilton *et al.*, 2017] with task-specific adaptations. (2) AutoML-based methods. We adopt F2GNN [Wei *et al.*, 2022] / LRGNN [Wei *et al.*, 2023] / Prof-CF [Wang *et al.*, 2022] for three tasks. (3) LLM-GNN. GNNs generated by LLMs. (4) LLMNet (GL) operates without external knowledge.

3.2 Performance Comparisons

Table 1 showcases the performance of LLMNet on twelve datasets across three tasks. LLMNet consistently outperforms all baselines, highlighting its ability to design effective GNNs for various graph learning tasks. The enhanced performance of LLMNet over LLMNet (GL) underscores the value of incorporating extracted knowledge into the GNN design process. Unlike AutoML methods that operate within a predefined design space, LLMNet (GL) leverages LLMs to expand this space, achieving comparable performance and validating the agents’ problem-solving capabilities. The LLM-GNN baseline, which relies solely on LLM suggestions without knowledge integration, faces challenges in understanding tasks and graphs, resulting in less effective GNN designs. LLMNet’s superior performance highlights the significance of knowledge in designing effective GNNs.

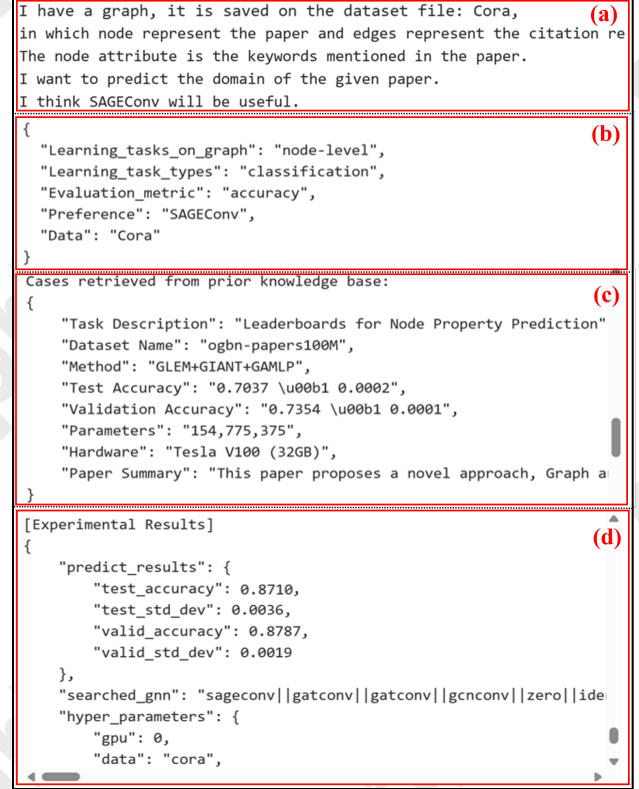


Figure 2: The detailed steps and output of LLMNet.

4 Demonstration

In this section, we demonstrate the use case of LLMNet on a real-world problem. For example, users aim to predict the category of articles within a citation network.

As shown in Figure 2, (a) illustrates the user’s input instructions, (b) displays the task plan generated by the Planning Agent, which interprets the user’s intention to predict the category of articles within a citation network as a node classification task. (c) shows the Data Agent retrieving relevant knowledge from the prior knowledge base, including methods for node classification. (d) displays the system’s experimental results and its designed GNN model, LLMNet achieves an accuracy of 0.8710 on the Cora dataset, surpassing the GNN-based baselines GCN at 0.8568, ACM-GCN at 0.8667 (Detailed experiments is in the extended version), and the AutoML-based baseline SANE at 0.8640.

This demonstration showcases the effectiveness of LLMNet in automatically designing GNN model for real-world graph learning problems.

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